DYNAMICAL SYSTEMS APPROACH TO F(R) GRAVITY

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FIELD EQUATIONS OF F(R) GRAVITY

 Field equations are derived from the generalised form of the Einstein Hilbert Lagrangian:

$$S = \int \left[f(R) + \mathcal{L}_M \right] \sqrt{-g} d^4 x$$

• f(R) is a generic function of the Ricci scalar taking the form:

• f(R) = R + g(R) so that we regain GR when g(R) = 0

COSMOLOGICAL FIELD EQUATIONS FOR F(R) GRAVITY - FLRW METRIC

Modified Friedmann Equation

$$H^{2} = \frac{1}{3f'} \left(\rho + \frac{1}{2} \left(Rf' - f \right) - 3H\dot{R}f'' \right)$$

Modified Raychaudhury Equation

$$2\dot{H} + 3H^2 = -\frac{1}{f'} \left(P + 2H\dot{R}f'' + \frac{1}{2} \left(f - Rf' \right) + \dot{R}^2 f''' + \ddot{R}f'' \right)$$

Trace Equation of modified field equations

 $3\ddot{R}f'' = \rho(1 - 3w) + f'R - 2f - 9Hf''\dot{R} - 3f'''\dot{R}^2.$

The Hu-Sawicki model is a class of broken power law functions which are constructed to evade solar system tests, provide the late time accelerated expansion observed.

$$f(R) = R - m^2 \frac{c_1 \left(\frac{R}{m^2}\right)^n}{c_2 \left(\frac{R}{m^2}\right)^n + 1}$$

$$m^{2} \equiv \frac{\kappa^{2} \bar{\rho}_{0}}{3} = (8315 M pc)^{-2} \left(\frac{\Omega_{m} h^{2}}{0.13}\right)$$

The parameters of the model:

 n>0
 c₁ and c₂ are dimensionless parameters

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$$\lim_{\frac{m^2}{R} \to 0} f(R) \approx R - \frac{c_1}{c_2} m^2$$

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This term encapsulates the

cosmological constant

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setting the plateau of the corrective term equal to 2A we obtain the following relationship between the constants and the energy densities of the cosmological constant and the matter content:

$$\frac{c_1}{c_2} \approx 6 \frac{\Omega_{\Lambda}}{\Omega_m} = 6 \frac{(1 - \Omega_m)}{\Omega_m}$$

DYNAMICAL SYSTEMS APPROACH TO F(R) GRAVITY

- Need to express the cosmological equations (Modified Friedmann, modified Raychaudhury)
 - in terms of a set of generalised dynamical variables

- USE A COMPACT PHASE SPACE
 - Define a POSITIVE DEFINITE normalisation,
 D, to bring all solutions to exist within a finite compact volume in the general phase space
 - Define a normalised time variable as:

$$\frac{d}{d\tau} \equiv \frac{1}{D} \frac{d}{dt}$$

- as a set of autonomous differential equations
- Define a set of normalised, general dynamical system variables

DYNAMICS OF THE GENERAL F(R) - COMPACT ANALYSIS

POSITIVE NORMALISATION

 Any negative contribution to the Friedmann equation must be absorbed into the normalisation

$$\left(3H + \frac{3}{2}\frac{\dot{f}'}{f'}\right)^2 + \frac{3}{2}\frac{f}{f'} = \frac{3\rho_m}{f'} + \frac{3}{2}R + \left(\frac{3}{2}\frac{\dot{f}}{f'}\right)^2$$
$$D^2 = \left(3H + \frac{3}{2}\frac{\dot{f}'}{f'}\right)^2 + \frac{3}{2}\frac{f}{f'}$$

 LHS defines a positive definite quantity that we use as the normalisation

DYNAMICS OF THE GENERAL F(R) - COMPACT ANALYSIS

DYNAMICAL SYSTEMS VARIABLES

 From the other terms in the Friedmann equation, we can now neatly define the dynamical system variables

system constraints

Friedmann $1 = \Omega + x^2 + v$ Normalisation $1 = (Q + x)^2 + y$ $-1 \le x \le 1, \quad 0 \le \Omega \le 1, \quad -2 \le Q \le 2,$ $0 \le v \le 1, \quad 0 \le y \le 1$

$$\left(3H + \frac{3}{2}\frac{\dot{f}'}{f'}\right)^2 + \frac{3}{2}\frac{f}{f'} = \frac{3\rho_m}{f'} + \frac{3}{2}R + \left(\frac{3}{2}\frac{\dot{f}}{f'}\right)^2$$

$$\begin{aligned} x &= \frac{3}{2} \frac{\dot{f}'}{f'} \frac{1}{D} & y &= \frac{3}{2} \frac{f}{f'} \frac{1}{D^2} \\ v &= \frac{3}{2} \frac{R}{D^2} & \Omega &= \frac{3\rho_m}{f'} \frac{1}{D^2} \\ Q &= \frac{3H}{D} & D^2 &= \left(3H + \frac{3}{2}\frac{\dot{f}'}{f'}\right)^2 + \frac{3}{2}\frac{f}{f'} \end{aligned}$$

PROPAGATION EQUATIONS

Differentiating each dynamical variable, substituting in the modified cosmological field equations and then eliminating variables y and Ω using the constraints, we obtain a 3 dimensional system of first order autonomous differential equations :

$$\frac{dv}{d\tau} = -\frac{1}{3}v \left[(Q+x) \left(2v + 4xQ - (1-v-x^2) (1+3w) \right) - 2Q - 4x + 2x\Gamma (v-1) \right],$$

$$\frac{dx}{d\tau} = \frac{1}{6} \left[-2x^2v\Gamma + (1-v-x^2) (1-3w) + 2v + 4(x^2-1) (1-Q^2-xQ) + x(Q+x) \left((1-v-x^2) (1+3w) - 2v \right) \right],$$

$$\frac{dQ}{d\tau} = \frac{1}{6} \left[-4xQ^3 + (5+3w) Qx (1-xQ) - Q^2 (1-3w) - Qx^3 (1+3w) - 3vQ (1+w) (Q+x) + 2v (1-\Gamma Qx) \right].$$



this term specifies the model to be input into the above general propagation equations. Γ must be expressible in terms of the dynamical system variables to close the system

PROPAGATION EQUATIONS

f''K

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$$\Gamma \equiv \frac{f'}{2\pi\pi^2}$$
The above system characterises a GENERAL dynamical system for any modified gravity cosmology defined by a function f(B), which is

invertible in terms of the DS variables, so we can determine $\Gamma(x,Q,v)$

DYNAMICS OF THE HU SAWICKI MODEL

Define the following relations

$$m^2 \equiv CH_0^2$$

 $r \equiv \frac{R}{H_0^2}$
 $h \equiv \frac{H}{H_0}$

And rewrite the HS model as:

$$f(R) = CH_0^2 \left[\left(\frac{r}{C}\right) - \frac{c_1 \left(\frac{r}{C}\right)^n}{c_2 \left(\frac{r}{C}\right)^n + 1} \right]$$

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 $m^{2} \equiv CH_{0}^{2}$ $r \equiv \frac{R}{H_{0}^{2}}$ $h \equiv \frac{H}{H_{0}}$

And rewrite the HS model as:

$$f(R) = CH_0^2 \left| \left(\frac{r}{C}\right) - \frac{\left(\frac{r}{C}\right)}{c_2\left(\frac{r}{C}\right) + 1} \right|$$

a compact dynamical systems analysis can only be done for for a very special HS model: $n = 1, c_1 = 1$

$$\Gamma \equiv \frac{f'}{f''R} = \frac{1}{2} \frac{vy}{\left(v-y\right)^2}$$

Fixed points for v = y = 0appear in DSA for any f(R)

PHASE SPACE









RESULTS - DSATO HS

Table I. Fixed points and associated exact solutions

Point	Coordinate (Q, x, y, v, Ω)	Scale factor evolution, $a(t)$
\mathcal{A}_{\pm}	$\pm \frac{1}{\sqrt{2}}, 0, \frac{1}{2}, 1, 0$	$a(t) = a_0 e^{H_0(t-t_0)}$
\mathcal{B}_{\pm}	$\left[\pm\frac{2}{3},\pm\frac{1}{3},0,\frac{8}{9},0\right]$	$a(t) = a_0 e^{H_0(t-t_0)}$
C(w = -1)	$0, \sqrt{\frac{3(w+1)}{1+3w}}, -\frac{2}{1+3w}, 0, -\frac{2}{1+3w}$	$a(t) = a_0$
$\mathcal{D}(w = -1)$	$\left[0, -\sqrt{\frac{3(w+1)}{1+3w}}, -\frac{2}{1+3w}, 0, -\frac{2}{1+3w}\right]$	$a(t) = a_0$
ε	[0, 1, 0, 0, 0]	$a(t) = a_0$
${\cal F}$	[0, -1, 0, 0, 0]	$a(t) = a_0$
\mathcal{G}_{\pm}	$[\pm 2, \mp 1, 0, 0, 0]$	$a(t) = a_0 \left(2H_0(t - t_0) + 1\right)^{\frac{1}{2}}$
$\mathcal{H}_{\pm}(w \leq rac{2}{3})$	$\left[\pm \frac{2}{3(w-1)}, \pm \frac{3w-1}{3(w-1)}, 0, 0, -\frac{4}{9} \frac{3w-2}{(w-1)^2} \right]$	$a(t) = a_0 \left(2H_0(t - t_0) + 1\right)^{\frac{1}{2}}$
\mathcal{J}	[0, 0, 1, 1, 0]	$a(t) = a_0$
\mathcal{K}_{\pm}	$\left[\pm \frac{\sqrt{6}}{3}, 0, \frac{1}{3}, \frac{1}{3}, \frac{2}{3}\right]$	$a(t) = a_0 \left(\frac{3}{2} H_0 \left(t - t_0\right) + 1\right)^{\frac{2}{3}}$

RESULTS - DSATO HS





EXPANSION HISTORY

We use a finite dynamical system to study the expansion behaviour of the HS model we analysed in the compact phase space. We can do this because the interesting de Sitter and radiation like fixed points are all finite points. To do finite, NON COMPACT analysis we use the following non compact DS variables:

$$x = \frac{\dot{f'}}{f'} \frac{1}{hH_0}, \quad v = \frac{1}{6} \frac{R}{h^2 H_0^2},$$
$$y = \frac{1}{6} \frac{f}{f'} \frac{1}{h^2 H_0^2}, \quad \Omega = \frac{1}{3} \frac{\rho_m}{f'} \frac{1}{h^2 H_0^2}$$

$$1 = \Omega + v - x - y$$
$$\Gamma \equiv \frac{f'}{f''R} = \frac{1}{2} \frac{vy}{(v-y)^2}$$

Propagation equations

$$\begin{aligned} \frac{dx}{dz} &= \frac{1}{(z+1)} \left[\left(-1 + 3w \right) \Omega + x^2 + (1+v) x - 2v + 4y \right], \\ \frac{dy}{dz} &= \frac{1}{(z+1)} \left[vx\Gamma - xy + 4y - 2yv \right], \\ \frac{dv}{dz} &= \frac{-\frac{v}{(z+1)} \left[\left(x\Gamma + 4 - 2v \right) \right], \\ \frac{d\Omega}{dz} &= \frac{1}{(z+1)} \left[\Omega \left(-1 + 3w + x + 2v \right) \right], \\ \frac{dh}{dz} &= \frac{h}{z+1} \left[2 - v \right] \end{aligned}$$

EXPANSION HISTORY

Setting the initial conditions of the DS variables below to their value at z=0, we integrate the system

$$\begin{aligned} x &= \frac{\dot{f'}}{f'} \frac{1}{hH_0}, \quad v = \frac{1}{6} \frac{R}{h^2 H_0^2}, \\ y &= \frac{1}{6} \frac{f}{f'} \frac{1}{h^2 H_0^2}, \quad \Omega = \frac{1}{3} \frac{\rho_m}{f'} \frac{1}{h^2 H_0^2} \end{aligned}$$

$$1 = \Omega + v - x - y$$

Propagation equations

$$\begin{aligned} \frac{dx}{dz} &= \frac{1}{(z+1)} \left[\left(-1 + 3w \right) \Omega + x^2 + \left(1 + v \right) x - 2v + 4y \right], \\ \frac{dy}{dz} &= \left[-\frac{1}{(z+1)} \left[vx\Gamma - xy + 4y - 2yv \right], \\ \frac{dv}{dz} &= \left[-\frac{v}{(z+1)} \left[\left(x\Gamma + 4 - 2v \right) \right], \\ \frac{d\Omega}{dz} &= \left[\frac{1}{(z+1)} \left[\Omega \left(-1 + 3w + x + 2v \right) \right], \\ \frac{dh}{dz} &= \frac{h}{z+1} \left[2 - v \right] \end{aligned}$$



SUMMARY OF EXPANSION HISTORY FOR z = 0

We see that this case (n=1, c=1)of the HS model does not do well to mimic the Λ CDM model :

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I. There are large deviations in the Hubble parameter



SUMMARY OF EXPANSION HISTORY FOR z = 0

We see that this case (n=1, c=1) of the HS model does not do well to mimic the Λ CDM model :

2. For f(R) gravity, in these dynamical variables, the deceleration parameter looks like:

$$q = 1 - \iota$$

while the deceleration parameter shows general behaviour that favours a late time accelerated epoch of expansion, it has the wrong asymptotic behaviour



Total Effective equation of state

FriedmannFrom Raychaudhury
$$H^2 = \frac{\rho_m}{3f'} + \frac{R}{6} - \frac{1}{6}\frac{f}{f'} - H\frac{\dot{f}'}{f'}$$
 $P_{tot} = H^2(2q-1)$ $3H^2 = \frac{\rho_m}{f'} + 3H^2 [v - y - x]$ $P_{tot} = g_{DE} = H^2(1 - 2v)$ $\Rightarrow \rho_{DE,eff} = 3H^2 [v - y - x]$ $P_{tot} = P_{DE} = H^2(1 - 2v)$

$$w_{total} = \frac{P_{total}}{\rho_{total}} = \frac{P_{tot}}{\rho_m + \rho_{DE,eff}}.$$

SUMMARY OF EXPANSION HISTORY FOR z=0

We see that this case (n=1, c=1)of the HS model does not do well to mimic the Λ CDM model :

3. The total effective equation of state has the wrong asymptotic behaviour. It represents a radiation like fluid being present until very late in the universe, in an analysis which was done entirely for dust.



This is consistent with the findingsof the dynamical systems analysis, as we found, that orbits most likely originated from radiation like fixed points and evolved toward de Sitter like points.

INITIAL VALUE OF CORRECTION FUNCTION: g(R)

Choosing the initial parameters to be exactly equal to their ACDM values TODAY is what compromised the agreement between the Hu-Sawicki model and the ACDM model.

In order for the model to mimic ACDM, the initial value of the Ricci scalar should lie on the plateau corresponding to the constant value of g(R)



To demonstrate the effects of placing the initial value of the correction on its function's plateau:

This trajectory in the phase space immediately shows an improvement, it evolves from an initially matter dominated era toward a de Sitter like expansion era.



To demonstrate the effects of placing the initial value of the correction on its function's plateau: The improvement in agreement in the calculated Hubble parameter and the ACDM model is obvious



To demonstrate the effects of placing the initial value of the correction on its function's plateau:

Setting the initial conditions further back in time has also visibly improved the asymptotic behaviour of the deceleration parameter



And finally, the correct asymptotic behaviour of the total effective equation of state has been achieved.

It appears to be dominated by dust until the quite recent past, thereafter a "fluid" with negative pressure begins to dominate the energy content.



CONCLUSIONS

- A dynamical systems analysis of a specific model in the Hu-Sawicki class of f(R) models for gravity, showed that that de Sitter attractors do exist in the phase space, as well as unstable radiation like points, and a non analytic matter like point.
- This choice was limited by the chosen DS framework which only permitted an analysis of the (n=1,c1=1) case
- In order for the Hu-Sawicki model to mimic the ACDM model, we need to ensure that the initial value of the correction is placed comfortably on the function's plateau. Setting the initial conditions to the ACDM values at z=20 set g(R) equal to its plateau value, thereby almost correcting the bad behaviour.

CONCLUSIONS

- The HS model can provide the desired properties, an expansion which accelerates at low red shifts without an explicit cosmological constant term representing an energy density, but only at the expense of the present values of q0 and H0.
- Initial conditions must be set at high redshifts, where the behaviour is understood, and integrated out to future, where we wish to investigate viability.

DYNAMICAL SYSTEMS APPROACH TO F(R) GRAVITY

- Need to express the cosmological equations (Modified Friedmann, modified Raychaudhury)
 - in terms of a set of generalised dynamical variables
 - as a set of autonomous differential equations

 A popular method is to define a set of expansion normalised, Hubble normalised, variables

$$H^{2} = \frac{1}{3f'} \left(\rho + \frac{1}{2} \left(Rf' - f \right) - 3H\dot{R}f'' \right)$$

- But such a state space is only compact for simple, expanding models, where the theory does not allow for recollapsing, bouncing or static universes
- This translates to: there is no contribution to the respective Friedmann equation allowing for zero valued or negative H(z)